HEF4046B-Q100

Phase-locked loop

Rev. 2 — 3 September 2024 Product data sheet

1. General description

The HEF4046B-Q100 is a phase-locked loop circuit that consists of a linear voltage controlled oscillator (VCO) and two different phase comparators with a common signal input amplifier and a common comparator input.

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 3) and is suitable for use in automotive applications.

2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 3)
  - Specified from -40 °C to +85 °C
- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Complies with JEDEC standard JESD 13-B
- ESD protection:
  - HBM: ANSI/ESDA/JEDEC JS-001 class 2 exceeds 2000 V
  - CDM: ANSI/ESDA/JEDEC JS-002 class C3 exceeds 1000 V

3. Ordering information

Table 1. Ordering information

Type number	Package			
	Temperature range	Name	Description	Version
HEF4046BT-Q100	-40 °C to +85 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1

4. Functional diagram

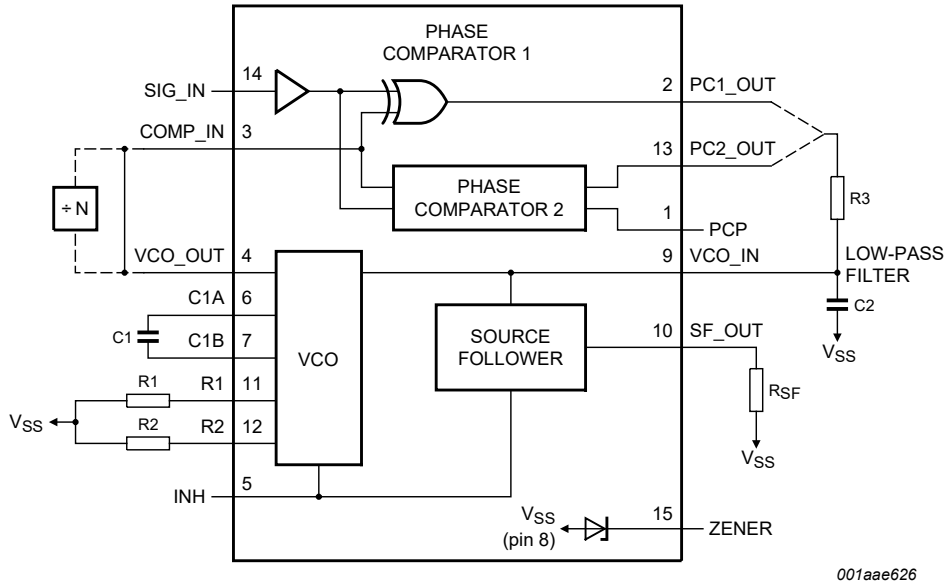
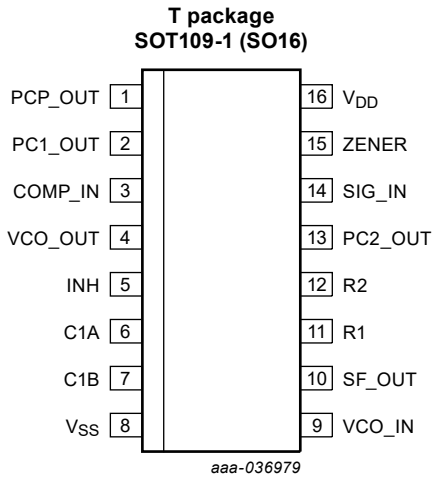


Fig. 1. Functional diagram

5. Pinning information

5.1. Pinning



5.2. Pin description

Table 2. Pin description

Symbol	Pin	Description
PCP_OUT	1	phase comparator pulse output
PC1_OUT	2	phase comparator 1 output
COMP_IN	3	comparator input
VCO_OUT	4	VCO output
INH	5	inhibit input
C1A	6	capacitor C1 connection A
C1B	7	capacitor C1 connection B
V_{SS}	8	ground supply voltage
VCO_IN	9	VCO input
SF_OUT	10	source-follower output
R1	11	resistor R1 connection
R2	12	resistor R2 connection
PC2_OUT	13	phase comparator 2 output
SIG_IN	14	signal input
ZENER	15	Zener diode input for regulated supply
V_{DD}	16	supply voltage

6. Functional description

6.1. VCO control

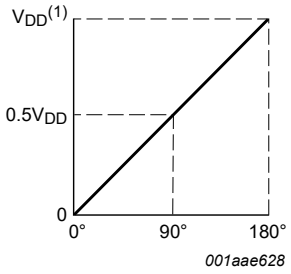
The VCO requires an external capacitor (C1) and resistor (R1) with an optional resistor (R2). Resistor R1 and capacitor C1 determine the frequency range of the VCO, while resistor R2 enables the VCO to have a frequency off-set if required. The high input impedance of the VCO simplifies the design of low-pass filters; it permits the designer a wide choice of resistor/capacitor ranges. In order not to load the low-pass filter, a source-follower output of the VCO input voltage is provided at SF_OUT (pin 10). If this is used, a load resistor (R_L) should be connected from SF_OUT to V_{SS}; if unused, SF_OUT should be left open. The VCO output (pin 4) can either be connected directly to the comparator input COMP_IN (pin 3) or via a frequency divider. A LOW-level at the inhibit input INH_IN (pin 5) enables the VCO and the source follower, while a HIGH-level turns both off to minimize standby power consumption.

6.2. Phase comparators

The phase-comparator signal input SIG_IN (pin 14) can be direct-coupled, provided the signal swing is between the standard HEF4000B family input logic levels. The signal must be capacitively coupled to the self-biasing amplifier at the signal input with smaller swings. Phase comparator 1 is an EXCLUSIVE-OR network. The signal and comparator input frequencies must have a 50% duty factor to obtain the maximum lock range. The average output voltage of the phase comparator is equal to $0.5V_{DD}$ when there is no signal or noise at the signal input. The average voltage to the VCO input VCO_IN is supplied by the low-pass filter connected to the output of phase comparator 1. This also causes the VCO to oscillate at the center frequency (f_0). The frequency capture range ($2f_C$) is defined as the frequency range of input signals on which the PLL will lock if it was initially out of lock. The frequency lock range ($2f_L$) is defined as the frequency range of input signals on which the loop will stay locked if it was initially in lock. The capture range is smaller or equal to the lock range.

With phase comparator 1, the range of frequencies over which the PLL can acquire lock (capture range) depends on the low-pass filter characteristics and this range can be made as large as the lock range. Phase comparator 1 enables the PLL system to remain in lock in spite of high amounts of noise in the input signal. A typical behavior of this type of phase comparator is that it may lock onto input frequencies that are close to harmonics of the VCO center frequency. Another typical behavior is that the phase angle between the signal and comparator input varies between 0° and 180°, and is 90° at the center frequency. Fig. 2 shows the typical phase-to-output response characteristic.

Fig. 3 shows the typical waveforms for a PLL with a f_0 locked phase comparator 1.



(1) Average output voltage.

Fig. 2. Signal-to-comparator inputs phase difference for comparator 1

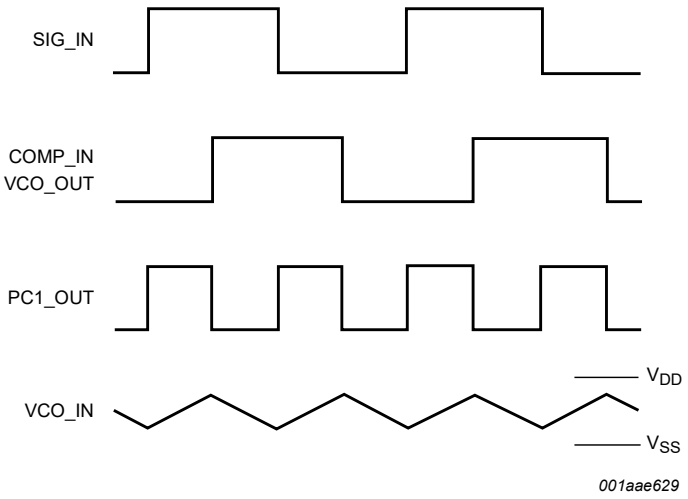


Fig. 3. Typical waveforms for phase-locked loop with an f_0 locked phase comparator 1

Phase comparator 2 is an edge-controlled digital memory network. It consists of four flip-flops, control gating and a 3-state output circuit comprising p and n-type drivers with a common output node. When the p-type or n-type drivers are ON, they pull the output up to V_{DD} or down to V_{SS} respectively. This type of phase comparator only acts on the positive-going edges of the signals at SIG_IN and COMP_IN. Therefore, the duty factors of these signals are not of importance.

If the signal input frequency is higher than the comparator input frequency, the p-type output driver is maintained ON most of the time, and both the n and p-type drivers are OFF (3-state) the remainder of the time. If the signal input frequency is lower than the comparator input frequency, the n-type output driver is maintained ON most of the time, and both the n and p-type drivers are OFF the remainder of the time. If the signal input and comparator input frequencies are equal, but the signal input lags the comparator input in phase, the n-type output driver is maintained ON for a time corresponding to the phase difference. If the comparator input lags the signal input in phase, the p-type output driver is maintained ON for a time corresponding to the phase difference. Subsequently, the voltage at the capacitor of the low-pass filter connected to this phase comparator is adjusted until the signal and comparator inputs are equal in both phase and frequency. At this stable point, both p and n-type drivers remain OFF and thus the phase comparator output becomes an open circuit and keeps the voltage at the capacitor of the low-pass filter constant.

Moreover, the signal at the phase comparator pulse output (PCP_OUT) is a HIGH level, which can be used for indicating a locked condition. Thus, for phase comparator 2, no phase difference exists between the signal and comparator inputs over the full VCO frequency range. Moreover, the power dissipation due to the low-pass filter is reduced when this type of phase comparator is used, because both p and n-type output drivers are OFF for most of the signal input cycle. It should be noted that the PLL lock range for this type of phase comparator is equal to the capture range, independent of the low-pass filter. With no signal present at the signal input, the VCO is adjusted to its lowest frequency for phase comparator 2. Fig. 4 shows typical waveforms for a PLL employing this type of locked phase comparator.

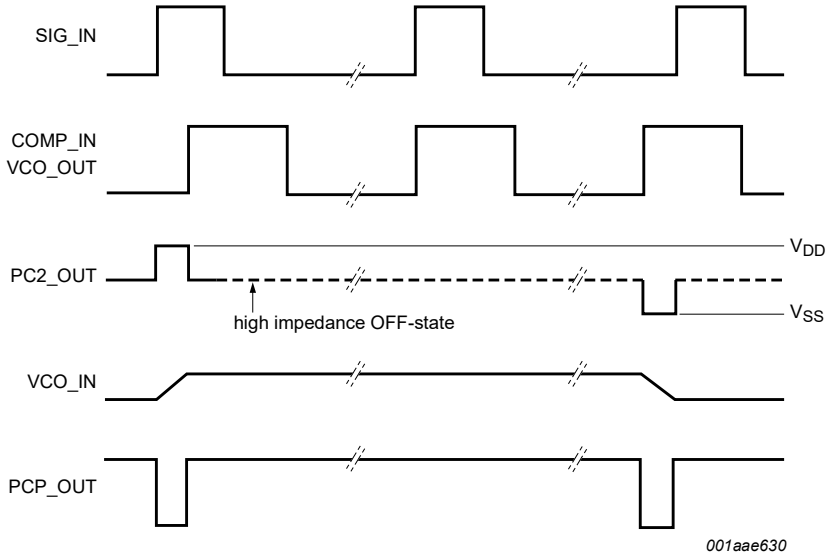


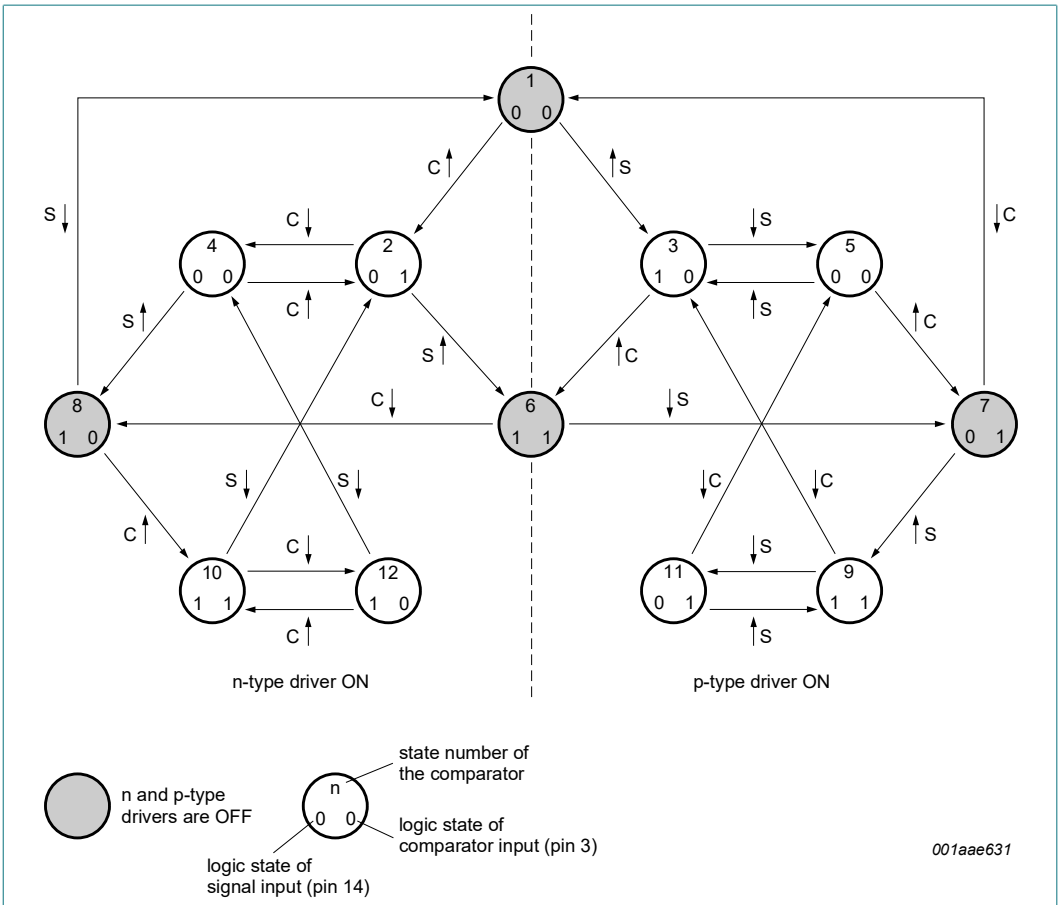
Fig. 4. Typical waveforms for phase-locked loop with a locked phase comparator 2

Fig. 5 shows the state diagram for phase comparator 2. Each circle represents a state of the comparator. The number at the top, inside each circle, represents the state of the comparator, while the logic state of the signal and comparator inputs are represented by a '0' for a logic LOW or a '1' for a logic HIGH, and they are shown in the left and right bottom of each circle.

The transitions from one to another result from either a logic change at the signal input (S representing SIG_IN) or the comparator input (C representing COMP_IN). A positive- going and a negative-going transition are shown by an arrow pointing up or down respectively.

The state diagram assumes, that only one transition on either the signal input or comparator input occurs at any instant.

- States 3, 5, 9 and 11 represent the output condition when the p-type driver is ON.
- States 2, 4, 10 and 12 determine the condition when the n-type driver is ON.
- States 1, 6, 7 and 8 represent the condition when the output is in its high-impedance OFF state; i.e. both p and n-type drivers are OFF, and the PCP_OUT output is HIGH. The condition at output PCP_OUT for all other states is LOW.



S ↑: 0 to 1 transition at the signal input SIG_IN.

C ↓: 1 to 0 transition at the comparator input COMP_IN.

Fig. 5. State diagram for comparator 2

7. Limiting values

Table 3. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DD}	supply voltage		-0.5	+18	V
I_{IK}	input clamping current	$V_I < -0.5$ V or $V_I > V_{DD} + 0.5$ V	-	±10	mA
V_I	input voltage		-0.5	$V_{DD} + 0.5$	V
I_{OK}	output clamping current	$V_O < -0.5$ V or $V_O > V_{DD} + 0.5$ V	-	±10	mA
$I_{I/O}$	input/output current		-	±10	mA
I_{DD}	supply current		-	50	mA
T_{stg}	storage temperature		-65	+150	°C
T_{amb}	ambient temperature		-40	+85	°C
P_{tot}	total power dissipation	-40 °C to +85 °C	-	500	mW
P	power dissipation	per output	-	100	mW

8. Recommended operating conditions

Table 4. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DD}	supply voltage		3	-	15	V
		as fixed oscillator only	3	-	15	V
		phase-locked loop operation	5	-	15	V
V_I	input voltage		0	-	V_{DD}	V
T_{amb}	ambient temperature	in free air	-40	-	+85	°C
Δt/ΔV	input transition rise and fall rate	for INH input				
		V_{DD} = 5 V	-	-	3.75	μs/V
		V_{DD} = 10 V	-	-	0.5	μs/V
		V_{DD} = 15 V	-	-	0.08	μs/V

9. Static characteristics

Table 5. Static characteristics

V_{SS} = 0 V; V_I = V_{SS} or V_{DD} unless otherwise specified.

Symbol	Parameter	Conditions	V_{DD}	T_{amb} = -40 °C		T_{amb} = +25 °C		T_{amb} = +85 °C		Unit
				Min	Max	Min	Max	Min	Max	
V_{IH}	HIGH-level input voltage	$\|I_O\|$ < 1 μA	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
V_{IL}	LOW-level input voltage	$\|I_O\|$ < 1 μA	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V_{OH}	HIGH-level output voltage	$\|I_O\|$ < 1 μA	5 V	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
V_{OL}	LOW-level output voltage	$\|I_O\|$ < 1 μA	5 V	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V
I_{OH}	HIGH-level output current	V_O = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	mA
		V_O = 4.6 V	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		V_O = 9.5 V	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		V_O = 13.5 V	15 V	-	-3.6	-	-3.0	-	-2.4	mA
I_{OL}	LOW-level output current	V_O = 0.4 V	5 V	0.52	-	0.44	-	0.36	-	mA
		V_O = 0.5 V	10 V	1.3	-	1.1	-	0.9	-	mA
		V_O = 1.5 V	15 V	3.6	-	3.0	-	2.4	-	mA
I_I	input leakage current		15 V	-	±0.3	-	±0.3	-	±1.0	μA
I_{OZ}	OFF-state output current	output HIGH and returned to V_{DD}	15 V	-	1.6	-	1.6	-	12.0	μA
		output LOW and returned to V_{SS}	15 V	-	1.6	-	1.6	-	12.0	μA

Symbol	Parameter	Conditions	V_{DD}		T_{amb} = -40 °C		T_{amb} = +25 °C		T_{amb} = +85 °C		Unit
					Min	Max	Min	Max	Min	Max	
I_{DD}	supply current	I_O = 0 A	5 V	[1]	-	-	20	-	-	-	µA
			10 V	[1]	-	-	300	-	-	-	µA
			15 V	[1]	-	-	750	-	-	-	µA
			5 V	[2]	-	20	-	20	-	150	µA
			10 V	[2]	-	40	-	40	-	300	µA
			15 V	[2]	-	80	-	80	-	600	µA
C_I	input capacitance	for INH input			-	-	-	7.5	-	-	pF

[1] Pin 15 open; pin 5 at V_{DD}; pins 3 and 9 at V_{SS}; pin 14 open.
[2] Pin 15 open; pin 5 at V_{DD}; pins 3 and 9 at V_{SS}; pin 14 at V_{DD}; input current at pin 14 not included.

10. Dynamic characteristics

Table 6. Dynamic characteristics

V_{SS} = 0 V; T_{amb} = 25 °C; C_L = 50 pF; input transition times ≤20 ns.

Symbol	Parameter	Conditions	V_{DD}	Min	Typ	Max	Unit
Phase comparators							
R_I	input resistance	SIG_IN input; at self-bias operating point	5 V	-	750	-	kΩ
			10 V	-	220	-	kΩ
			15 V	-	140	-	kΩ
$V_{i(sens)}$	input voltage sensitivity	SIG_IN input, AC coupled, peak-to-peak values; R1 = 10 kΩ; R2 = ∞; C1 = 100 pF; independent of the lock range	5 V	-	150	-	mV
			10 V	-	150	-	mV
			15 V	-	200	-	mV
V_{IL}	LOW-level input voltage	SIG_IN and COMP_IN inputs, DC coupled LOW; full temperature range	5 V	-	-	1.5	V
			10 V	-	-	3.0	V
			15 V	-	-	4.0	V
V_{IH}	HIGH-level input voltage	SIG_IN and COMP_IN inputs, DC coupled HIGH; full temperature range	5 V	3.5	-	-	V
			10 V	7.0	-	-	V
			15 V	11.0	-	-	V
I_{IH}	HIGH-level input current	SIG_IN input; at V_{DD}	5 V	-	7	-	µA
			10 V	-	30	-	µA
			15 V	-	70	-	µA
I_{IL}	LOW-level input current	SIG_IN input; at V_{SS}	5 V	-	-3	-	µA
			10 V	-	-18	-	µA
			15 V	-	-45	-	µA

Symbol	Parameter	Conditions	V_{DD}	Min	Typ	Max	Unit
VCO							
P	power dissipation	f_0 = 10 kHz; R1 = 1 MΩ; R2 = ∞; VCO_IN at 0.5 V_{DD}; see Fig. 9, Fig. 10, and Fig. 11	5 V	-	150	-	µW
			10 V	-	2500	-	µW
			15 V	-	9000	-	µW
f_{max}	maximum frequency	VCO_IN at V_{DD}; R1 = 10 kΩ; R2 = ∞; C1 = 50 pF	5 V	0.5	1.0	-	MHz
			10 V	1.0	2.0	-	MHz
			15 V	1.3	2.7	-	MHz
Δf/ΔT	frequency variation with temperature	no frequency offset (f_{min} = 0 Hz)	5 V [1]	-	0.22 to 0.30	-	% Hz/°C
			10 V [1]	-	0.04 to 0.05	-	% Hz/°C
			15 V [1]	-	0.01 to 0.05	-	% Hz/°C
		with frequency offset (f_{min} > 0 Hz)	5 V [1]	-	0 to 0.22	-	% Hz/°C
			10 V [1]	-	0 to 0.04	-	% Hz/°C
			15 V [1]	-	0 to 0.01	-	% Hz/°C
Δf/f	relative frequency variation	for VCO see Fig. 12 and Fig. 13					
		R1 > 10 kΩ	5 V	-	0.50	-	% Hz
		R1 > 400 kΩ	10 V	-	0.25	-	% Hz
		R1 = 1 MΩ	15 V	-	0.25	-	% Hz
δ	duty factor	VCO _OUT output	5 V	-	50	-	%
			10 V	-	50	-	%
			15 V	-	50	-	%
R_{in}	input resistance	for pin VCO_IN			10		MΩ
Source follower							
V_{offset}	offset voltage	R_L = 10 kΩ; VCO_IN at 0.5V_{DD}	5 V [2]	-	1.7	-	V
			10 V	-	2.0	-	V
			15 V	-	2.1	-	V
		R_L = 50 kΩ; VCO_IN at 0.5V_{DD}	5 V	-	1.5	-	V
			10 V	-	1.7	-	V
			15 V	-	1.8	-	V
Δf/f	relative frequency variation	VCO output; R_L > 50 kΩ; see Fig. 12	5 V	-	0.3	-	%
			10 V	-	1.0	-	%
			15 V	-	1.3	-	%
Zener diode							
V_Z	working voltage	I_Z = 50 µA	-	-	7.3	-	V
R_{dyn}	dynamic resistance	For internal zener diode; I_Z = 1 mA	-	-	25	-	Ω

[1] Over the recommended component range.
[2] The offset voltage is equal to the input voltage on pin VCO_IN minus the output voltage on pin SF_OUT.

11. Design information

Table 7. Design information

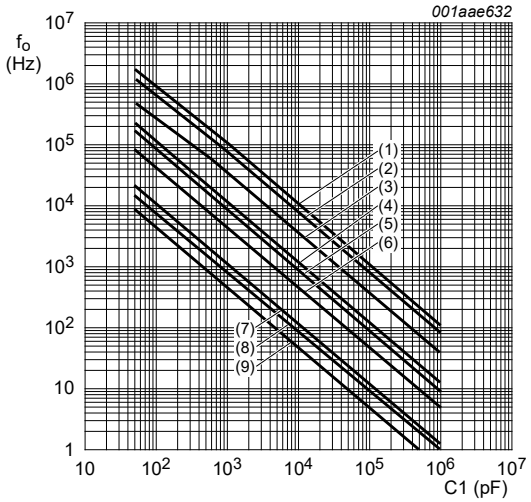
Test	Using phase comparator 1	Using phase comparator 2
VCO adjusts with no signal on SIG_IN	VCO in PLL system adjusts to center frequency (f_0)	VCO in PLL system adjusts to minimum frequency (f_{min})
Phase angle between SIG_IN and COMP_IN	90° at center frequency (f_0), approaching 0° and 180° at the ends of the lock range ($2f_L$)	always 0° in lock (positive-going edges)
Locks on harmonics of center frequency	yes	no
Signal input noise rejection	high	low
Lock frequency range ($2f_L$)	the frequency range of the input signal on which the loop will stay locked if it was initially in lock; $2f_L$ = full VCO frequency range = f_{max} - f_{min}	
Capture frequency range ($2f_c$)	the frequency range of the input signal on which the loop will lock if it was initially out of lock	
	depends on low-pass filter characteristics; $2f_c < 2f_L$	$2f_c = 2f_L$
Center frequency (f_0)	the frequency of the VCO when VCO_IN at $0.5V_{DD}$	

11.1. VCO component selection

Recommended range for R1 and R2: 10 kΩ to 1 MΩ.

Recommended range for C1: 50 pF to any practical value.

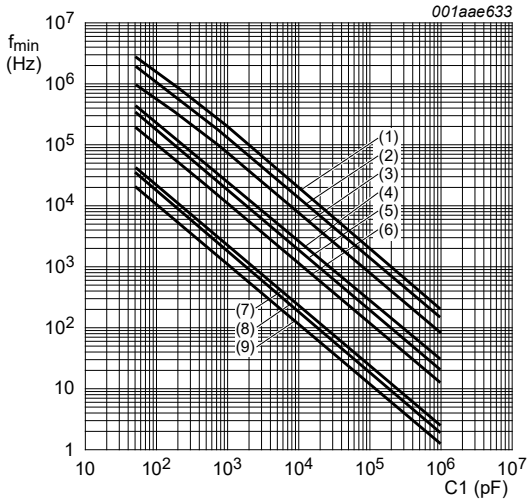
1. VCO without frequency offset (R2 = ∞).
   a. Given f_0: use f_0 with Fig. 6 to determine R1 and C1.
   b. Given f_{max}: calculate f_0 from $f_0 = 0.5f_{max}$; use f_0 with Fig. 6 to determine R1 and C1.
2. VCO with frequency offset.
   a. Given f_0 and $2f_L$: calculate f_{min} from the equation $f_{min} = f_0 - 2f_L$; use f_{min} with Fig. 7 to determine R2 and C1;
      calculate $\frac{f_{max}}{f_{min}}$ from the equation $\frac{f_{max}}{f_{min}} = \frac{f_0 + 2f_L}{f_0 - 2f_L}$;
      use $\frac{f_{max}}{f_{min}}$ with Fig. 8 to determine the ratio R2/R1 to obtain R1.
   b. Given f_{min} and f_{max}: use f_{min} with Fig. 7 to determine R2 and C1;
      calculate $\frac{f_{max}}{f_{min}}$;
      use $\frac{f_{max}}{f_{min}}$ with Fig. 8 to determine R2/R1 to obtain R1.



T_{amb} = 25 °C; VCO_IN at $0.5V_{DD}$; INH_IN at V_{SS}; R2 = ∞.

Lines (1), (4), and (7): V_{DD} = 15 V;
Lines (2), (5), and (8): V_{DD} = 10 V;
Lines (3), (6), and (9): V_{DD} = 5 V;
Lines (1), (2), and (3): R1 = 10 kΩ;
Lines (4), (5), and (6): R1 = 100 kΩ;
Lines (7), (8), and (9): R1 = 1 MΩ.

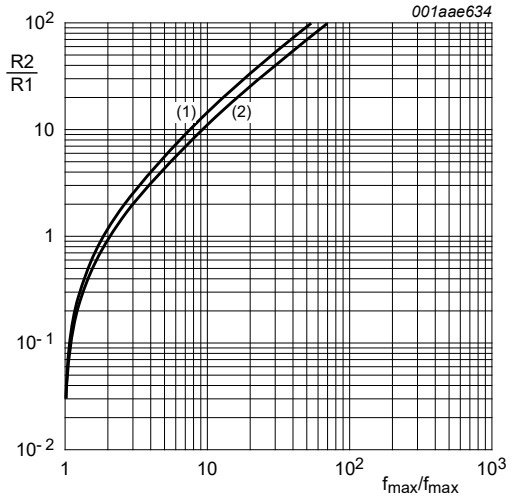
Fig. 6. Typical center frequency as a function of capacitor C1



T_{amb} = 25 °C; VCO_IN at V_{SS}; INH_IN at V_{SS}; R1 = ∞.

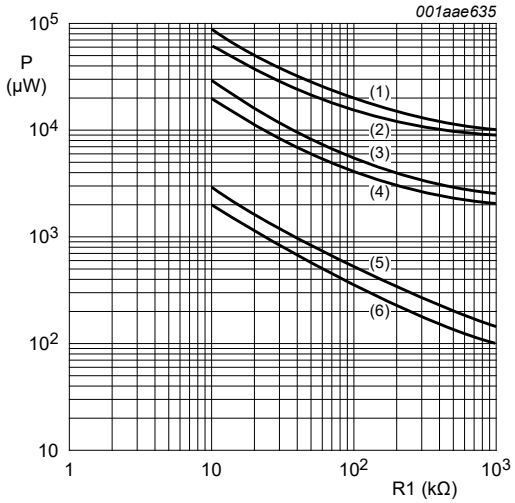
Lines (1), (4), and (7): V_{DD} = 15 V;
Lines (2), (5), and (8): V_{DD} = 10 V;
Lines (3), (6), and (9): V_{DD} = 5 V;
Lines (1), (2), and (3): R2 = 10 kΩ;
Lines (4), (5), and (6): R2 = 100 kΩ;
Lines (7), (8), and (9): R2 = 1 MΩ.

Fig. 7. Typical frequency offset as a function of capacitor C1



Line (1): V_{DD} = 5 V;
Line (2): V_{DD} = 10 V, 15 V.

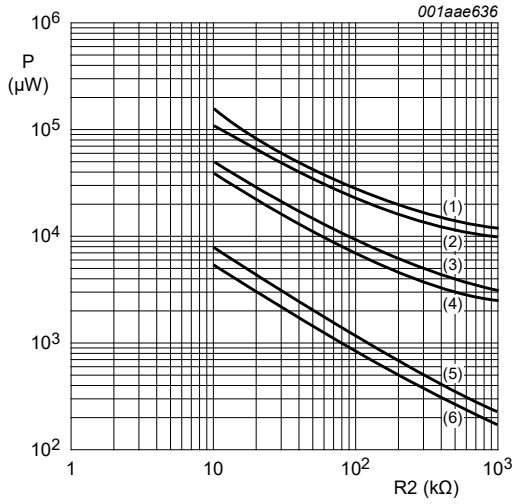
Fig. 8. Typical ratio of R2/R1 as a function of the ratio f_{max}/f_{min}



R2 = ∞; VCO_IN at $0.5V_{DD}$; C_L = 50 pF.

Lines (1) and (2): V_{DD} = 15 V;
Lines (3) and (4): V_{DD} = 10 V;
Lines (5) and (6): V_{DD} = 5 V;
Lines (1), (3), and (5): C1 = 50 pF;
Lines (2), (4), and (6): C1 = 1 μF.

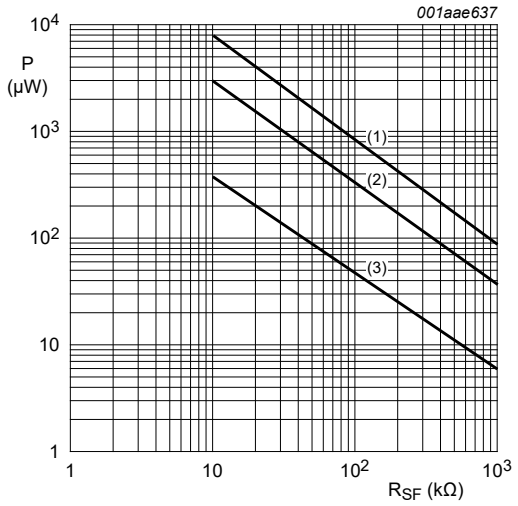
Fig. 9. Power dissipation as a function of R1



R1 = ∞; VCO_IN at V_{SS} (0 V); C_L = 50 pF.

Lines (1) and (2): V_{DD} = 15 V;
Lines (3) and (4): V_{DD} = 10 V;
Lines (5) and (6): V_{DD} = 5 V;
Lines (1), (3), and (5): C1 = 50 pF;
Lines (2), (4), and (6): C1 = 1 μF.

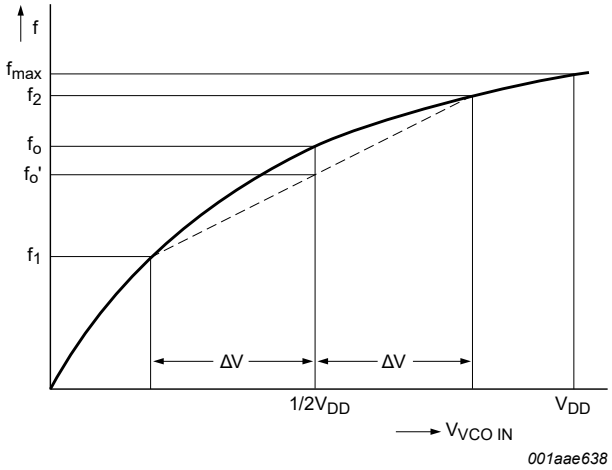
Fig. 10. Power dissipation as a function of R2



VCO_IN at 0.5V_{DD}; R1 = ∞; R2 = ∞.

Line (1): V_{DD} = 15 V;
Line (2): V_{DD} = 10 V;
Line (3): V_{DD} = 5 V.

Fig. 11. Power dissipation of source follower as a function of R_L



See Section 10.

For VCO linearity:

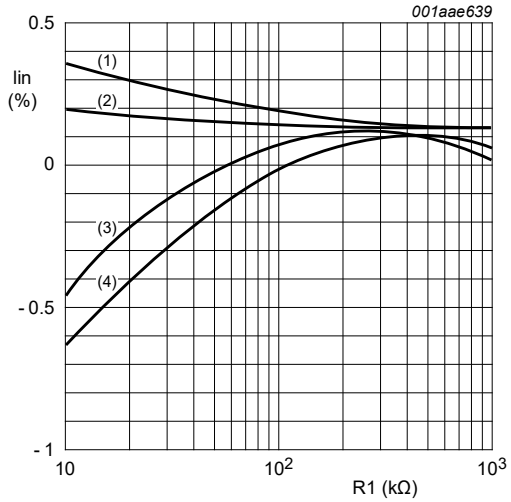
$$f'_0 = \frac{f_1 + f_2}{2}$$

$$\text{linearity} = \frac{f'_0 - f_0}{f'_0} \times 100\ \%$$

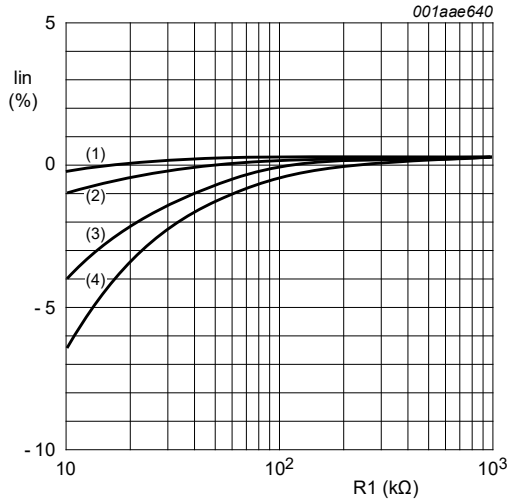
This figure and the above formula also apply to source follower linearity: substitute V_O at SF_OUT for f.

ΔV = 0.3 V at V_{DD} = 5 V;
ΔV = 2.5 V at V_{DD} = 10 V;
ΔV = 5.0 V at V_{DD} = 15 V.

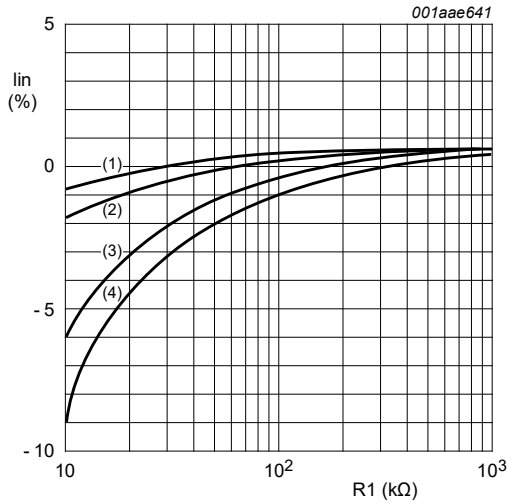
Fig. 12. Definition of linearity



a. V_{DD} = 5 V



b. V_{DD} = 10 V



c. V_{DD} = 15 V

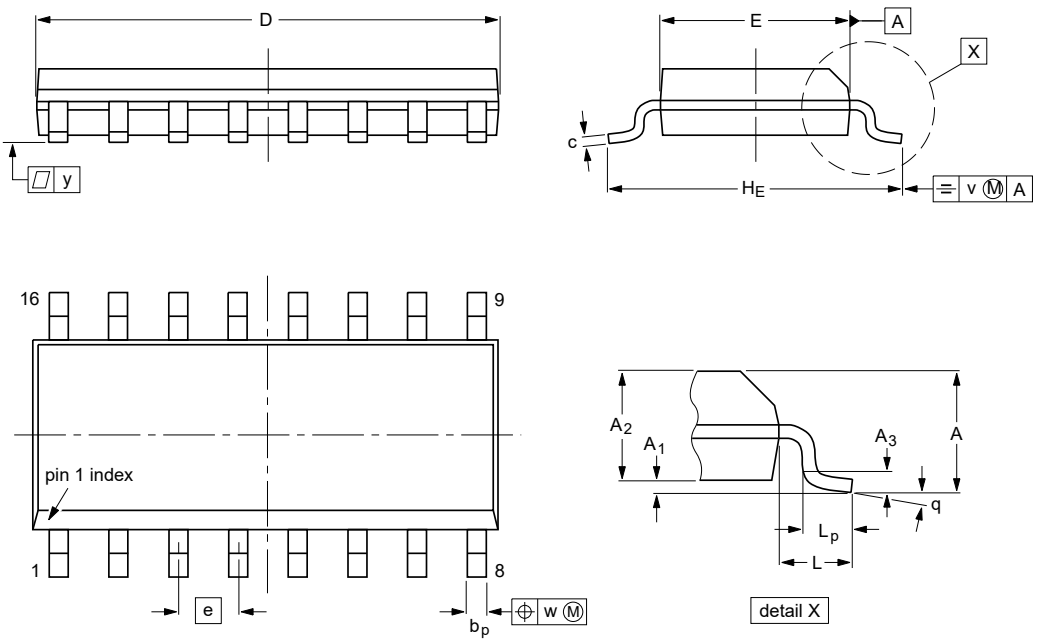
R2 = ∞;

Line (1): C1 = 1 µF;
Line (2): C1 = 1 nF;
Line (3): C1 = 100 pF;
Line (4): C1 = 50 pF.

Fig. 13. VCO frequency linearity as a function of R1

12. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm **SOT109-1**



Dimensions (inch dimensions are derived from the original mm dimensions)

Unit		A	A_1	A_2	A_3	b_p	c	$D^{(1)}$	$E^{(1)}$	e	H_E	L	L_p	v	w	y	θ
mm	max	1.75	0.25			0.51	0.25	10.0	4.0		6.2		1.27				8°
	nom				0.25					1.27		1.05		0.2	0.25	0.1	
	min		0.10	1.25		0.31	0.10	9.8	3.8		5.8		0.4				0°
inches	max	0.069	0.010			0.020	0.010	0.394	0.16		0.244		0.05				8°
	nom				0.01					0.05		0.041		0.008	0.01	0.004	
	min		0.004	0.049		0.012	0.004	0.386	0.15		0.228		0.016				0°

Note
1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

sot109-1_po

Outline version	References				European projection	Issue date
	IEC	JEDEC	JEITA			
SOT109-1		MS-012				~~03-02-19~~ 23-10-27

Fig. 14. Package outline SOT109-1 (SO16)

13. Abbreviations

Table 8. Abbreviations

Acronym	Description
ANSI	American National Standards Institute
CDM	Charged Device Model
CMOS	Complementary Metal-Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
ESDA	ElectroStatic Discharge Association
HBM	Human Body Model
JEDEC	Joint Electron Device Engineering Council
PLL	Phase-Locked Loop

14. Revision history

Table 9. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4046B_Q100 v.2	20240903	Product data sheet	-	HEF4046B_Q100 v.1
Modifications:	• Section 2: ESD specification updated according to the latest JEDEC standard. • Fig. 14: Aligned SO package outline drawing to JEDEC MS-012			
HEF4046B_Q100 v.1	20231020	Product data sheet	-	-

15. Legal information

Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.
[2] The term 'short data sheet' is explained in section "Definitions".
[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the internet at https://www.nexperia.com.

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