

MLFB-Ordering data

6SL3230-1YE22-0UF0



Figure similar

Client order no. : Order no. : Offer no. : Remarks :

Item no. :
Consignment no. :
Project :

Rated data			General tech	General tech. specifications	
nput			Power factor λ	0.70 0.85	
Number of phases	3 AC		Offset factor cos φ	0.96	
Line voltage	380 480 V +10 % -20 %		Efficiency η	0.98	
Line frequency	47 63 Hz		Sound pressure level (1m)	63 dB	
Rated voltage	400V IEC	480V NEC	Power loss	0.181 kW	
Rated current (LO)	12.00 A	12.00 A	Filter class (integrated)	Unfiltered	
Rated current (HO)	9.27 A	9.75 A			
utput			EMC category (with accessories)	without	
Number of phases	3 AC				
Rated voltage	400V IEC	480V NEC	Ambient conditions		
Rated power (LO)	5.50 kW	7.50 hp	Standard board coating type	Class 3C3, according to IEC 6072 3: 2002	
Rated power (HO)	4.00 kW	5.00 hp			
Rated current (LO)	13.20 A	11.00 A	Cooling	Air cooling using an integrated f	
Rated current (HO)	10.20 A	7.60 A			
Rated current (IN)	13.60 A		Cooling air requirement	0.009 m³/s (0.325 ft³/s)	
Max. output current	18.00 A		Installation altitude	1000 m (3280.84 ft)	
Pulse frequency	4 kHz		Ambient temperature		
Output frequency for vector control	0 200 Hz		Operation	-20 45 °C (-4 113 °F)	
			Transport	-40 70 °C (-40 158 °F)	
Output frequency for V/f control	0 550 Hz		Storage	-25 55 °C (-13 131 °F)	
			Relative humidity		
				95 % At 40 °C (104 °F), condens	

Max. operation

95 % At 40 $^\circ C$ (104 $^\circ F), condensation and icing not permissible$

Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time



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Mechanical data		Closed-loop co	Figure sim		
Degree of protection	IP20 / UL open type		······································		
Size	FSB	V/f linear / square-law / parameter	rizable Yes		
Net weight	6 kg (12.85 lb)	V/f with flux current control (FCC)	Yes		
-	-	V/f ECO linear / square-law	Yes		
Width	100 mm (3.94 in)	Sensorless vector control	Yes		
Height	275 mm (10.83 in)	Vector control, with sensor	No		
Depth	218 mm (8.58 in)	Encoderless torque control	Yes		
Inputs / out	tputs				
tandard digital inputs		Torque control, with encoder	No		
Number	6	Communication			
Switching level: 0→1	11 V	Communication	PROFINET, EtherNet/IP		
Switching level: 1→0	5 V				
Max. inrush current	15 mA	Connections			
ail-safe digital inputs		Signal cable			
Number	1	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)		
Digital outputs		Line side			
Number as relay changeover contact	2	Version	screw-type terminal		
Output (resistive load)	DC 30 V, 5.0 A	Conductor cross-section	1.50 6.00 mm² (AWG 16 AWG 10)		
Number as transistor	0	Motor end			
Analog / digital inputs		Version	Screw-type terminals		
Number	2 (Differential input)	Conductor cross-section	1.50 6.00 mm² (AWG 16 AWG 10)		
Resolution	10 bit		(//// 10 ///// 10)		
witching threshold as digital in	put	DC link (for braking resistor)			
0→1	4 V	PE connection	On housing with M4 screw		
1→0	1.6 V	Max. motor cable length			
	1.0 V	Shielded	150 m (492.13 ft)		
nalog outputs		Unshielded	300 m (984.25 ft)		
Number	1 (Non-isolated output)				
PTC/ KTY interface					

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\mathrm{C}$

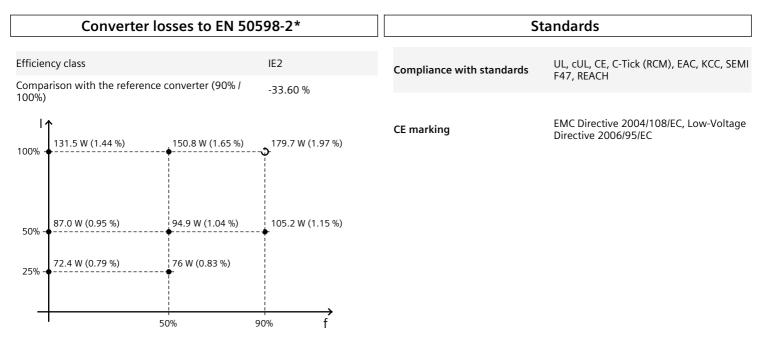


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The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values