Full-Brick AC-DC Converter 90 - 290 V AC Input

28 V DC Output

18 A Current

Negative logic

Description

The ADF18S28B is a new generation isolated AC-DC converter that uses an industry standard full-brick structure, featuring high efficiency and power density with low output ripple and noise. It operates from an input voltage range of 90 V AC to 290 V AC, and provides the rated output voltage of 28 V DC as well as the maximum output current of 18 A.

Operational Features

- Rated input voltage: 110/220 V AC
- Output current: 0 18 A
- Efficiency: 92% (28 V DC, 18 A)

Mechanical Features

- Industry standard full-brick (L x W x H): 116.8 mm x 61.0 mm x 12.7 mm (4.60 in. x 2.40 in. x 0.50 in.)
- Weight: 190 g

Control Features

- Remote on/off
- Remote sense

•

- Output voltage Trim
- PMBus communication

Protection Features

- Input undervoltage protection
- Input overvoltage protection
 - Output overcurrent protection (Self-recovery)
- Output overvoltage protection (Latch off)
- Output short circuit protection (Self-recovery)
- Overtemperature protection (Self-recovery)

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ADF18S28B

Safety Features

- TUV, UL, CE certification
- Meet UL60950-1, EN 60950-1 and IEC 60950-1
- Meet RoHS6 requirement

Applications

- Servers/Storages
- Routers/Switches
- Telecommunications equipment
- Enterprise networks



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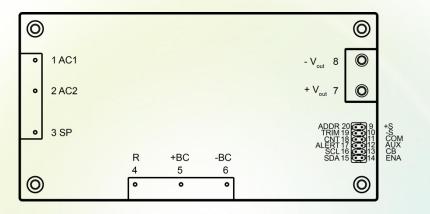
Designation Explanation

| <u>ADF</u> | <u>18</u> | <u>S</u> | <u>28</u> | <u>B</u> |
|------------|-----------|----------|-----------|----------|
| | - | - | | _ |

- 1 2 3 4 5
- 1 AC input, digital control, full-brick
- 2 Output current: 18 A
- 3 Single output
- 4 Output voltage: 28 V
- 5 With a baseplate

Mechanical Diagram

Pin Description

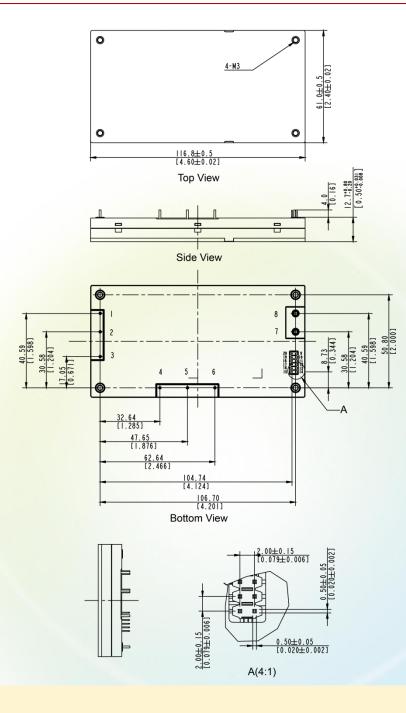


| Pin No. | Name | Function | Pin No. | Name | Function |
|---------|-------------------|--|---------|-------|---|
| 1 | AC1 | | 11 | СОМ | Common ground |
| 2 | AC2 | AC input | 12 | AUX | Auxiliary power supply |
| 3 | SP | Surge protection | 13 | СВ | Current balance for parallel operation |
| 4 | R | External resistor for inrush current protection | 14 | ENA | Enable signal or input power failure signal |
| 5 | +BC | Boost output voltage (+) | 15 | SDA | PMBus serial data line |
| 6 | -BC | Boost output voltage (-) | 16 | SCL | PMBus serial clock line |
| 7 | +V _{out} | Output voltage (+) | 17 | ALERT | PMBus alert |
| 8 | -V _{out} | Output voltage (-) | 18 | CNT | On/Off control (output side) |
| 9 | +S | Remote sense (+) | 19 | TRIM | Adjustment of output voltage |
| 10 | -S | Remote sense (-) | 20 | ADDR | Module address |





Mechanical Diagram



- All dimensions in mm [in.]. Tolerances: x.x ± 0.5 mm [x.xx ± 0.02 in.] x.xx ± 0.25 mm [x.xx ± 0.010 in.] except special declaration.
- 2. Pin 1 6 are 1.00 ± 0.05 mm [0.039 ± 0.002 in.] diameter, pin 7 and pin 8 are 2.0 ± 0.05 mm [0.079 ± 0.002 in.] diameter.
- 3. Unit: MKS

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Electrical Specifications

| Parameter | Min. | Тур. | Max. | Unit | Notes & Conditions |
|--|-------|---------|-------|------|--|
| Environment characteristics | | | | | • |
| Operating ambient temperature | -40 | - | 85 | °C | - |
| Storage and transportation temperature | -55 | - | 125 | ٥C | - |
| Operating and storage humidity | 10 | - | 95 | %RH | Non-condensing |
| Altitude range | 0 | - | 5000 | m | Certification: 4000 m |
| Baseplate temperature | -40 | - | 90 | °C | - |
| Absolute maximum ratings | - | | | | |
| Input voltage Continuous | - | - | 315 | V AC | - |
| Baseplate temperature | - | | 90 | °C | Conduction cooled |
| Voltage to SCL/SDA/ADDR/CB | - | - | 3.6 | V | - |
| Module number of parallel operation | - | - | 2 | pcs | - |
| Input characteristics | | | | | |
| Operating input voltage | 90 | - | 290 | V AC | - |
| Rated input voltage | 100 | 110/220 | 240 | V AC | - |
| Maximum input current | - | - | 8 | А | V _{in} = 90 V AC, 100% load |
| Innut innuch aumant | - | - | 20 | А | V _{in} = 110 V AC |
| Input inrush current | - | - | 40 | А | V _{in} = 220 V AC |
| Input frequency | 47 | 50/60 | 63 | Hz | - |
| Power factor | 0.95 | - | - | - | $T_A = 25^{\circ}$ C, $V_{in} = 110/220$ V AC, 100% load |
| Total harmonic distortion (THD) | - | - | 10 | % | $T_A = 25^{\circ}C, V_{in} = 110/220 V AC, P_{out} = 500 W$ |
| No-load loss | - | - | 10 | W | T _A = 25°C, V _{in} = 110 V AC |
| 100-1040 1033 | - | - | 12 | W | $T_A = 25^{\circ}C, V_{in} = 220 V AC$ |
| Standby power loss | - | - | 5 | W | T _A = 25°C, V _{in} = 110/220 V AC |
| Output characteristics | | | | | |
| Output voltage trim range | 20 | - | 32 | V DC | By I2C or analog, the analog mode takes priority over the I2C mode |
| Output voltage set point | 27.72 | 28.00 | 28.28 | V DC | $T_A = 25^{\circ}C, V_{in} = 110/220 V AC, 50\%$ load |
| Output power | - | - | 500 | W | See Figure 3 |

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Electrical Specifications

| Parameter | Min. | Тур. | Max. | Unit | Notes & Conditions |
|--|--------------|------|---------------|----------------------|--|
| Output characteristics | • | • | • | | |
| Line regulation | -0.3 | - | 0.3 | % | V _{out} = 28 V DC, P _{out} = 500 W |
| Load regulation | -0.8 | - | 0.8 | % | - |
| Regulated voltage precision | -3 | - | 3 | % | The whole range of $V_{in},I_{out}andT_A$ |
| Temperature coefficient | -0.02 | - | 0.02 | %/°C | The whole range of V_{in} , I_{out} and T_A |
| | 470×3 | - | 470×11 | μF | Output capacitor: low ESR aluminum capacitor (Recommend product model: EKY-630ELL471MK25S NCC) |
| External load capacitor | 390 | - | 390×2 | μF | Boost voltage bulk capacitor: long life aluminum capacitor (Recommend product model: ELXS451VSN391MR50S NCC) |
| | - | - | 320 | mV | -5°C ≤ T _A ≤ 85°C Oscilloscope bandwidth: 20 MHz |
| Output ripple and noise (peak to peak) | - | - | 640 | mV | $-25^{\circ}C \le T_{A} < -5^{\circ}C$ Oscilloscope bandwidth: 20 MHz |
| | - | - | 640 | mV | -40°C ≤ T _A < -25°C Oscilloscope bandwidth: 20 MHz |
| Hold up time | 10 | - | - | ms | Output capacitor: 470 μ F \times 3 Bulk capacitor: 390 μ F T _A = 25°C, 100% load, from input power outage drop to 90%V _{out} |
| Output voltage delay time | - | - | 8 | s | From V _{in} connection to 10%V _{out} |
| | - | | 100 | ms | From 10%V _{out} to 90%V _{out} , T _A ≥ -25°C |
| Output voltage rise time | - | - | 400 | ms | From $10\%V_{out}$ to $90\%V_{out}$, - $40^{\circ}C \le T_A < -25^{\circ}C$ When the temperature is below -25°C, there are no requirement on the output voltage rise waveform |
| Output voltage overshoot | - | - | 5 | % | The whole range of V_{in} , I_{out} and T_A |
| Current sharing accuracy | -10 | - | 10 | % | Each output power > 200 W. The voltage difference between parallel modules should be less than 5% |
| Protection characteristics | | | | | |
| Input undervoltage protection Startup threshold Shutdown threshold Hysteresis | - 74 5 | - | 90 85 - | V AC V AC V AC | - |



Electrical Specifications

| Parameter | Min. | Тур. | Max. | Unit | Notes & Conditions |
|---|-----------------|------|---------------|----------------------|---|
| Protection characteristics | • | | | • | |
| Input overvoltage protection Startup threshold Shutdown threshold Hysteresis | 290 295 5 | | - 310 - | V AC V AC V AC | - |
| Output overvoltage protection | - | - | 37 | V | Latch off |
| Output overcurrent protection | 105 | - | 150 | % | Self-recovery |
| Output short circuit protection | - | - | - | - | Self-recovery; The converter is not damaged even with long-term short circuits |
| Overtemperature protection Baseplate Hysteresis | 95 5 | - | - | ℃ ℃ | Self-recovery; The values are obtained by measuring the temperature of the middle of the baseplate |
| Dynamic characteristics | | | | | |
| Overshoot amplitude Recovery time | - | - | 5 250 | % µs | $T_{A} = 25^{\circ}C, V_{in} = 110/220 V AC$ Current change rate: 0.1 A/µs, Load: 25% - 50% - 25%; 50% - 75% - 50% |
| Efficiency | - | - | • | | • |
| 100% load | 88 | 89 | - | % | T _A = 25°C, V _{in} = 110 V AC; I _{out} = 18 A |
| 100% 1080 | 91 | 92 | - | % | T _A = 25°C, V _{in} = 220 V AC; I _{out} = 18 A |
| 50% load | 88 | 89 | - | % | T _A = 25°C, V _{in} = 110 V AC; I _{out} = 9 A |
| 50% 10au | 90 | 92 | - | % | $T_A = 25^{\circ}C, V_{in} = 220 V AC; I_{out} = 9 A$ |
| Other characteristics | | | | | |
| Remote on/off voltage Low level High level | 0 2.4 | - | 0.8 3.5 | V V | Negative logic |
| AUX | 10 | - | 14 | V | Auxiliary power output, the output current is less than 20 mA |
| ENA | - | - | - | - | See Enable (ENA) |
| +S | - | - | 5 | %V _{out} | San Remote Conce |
| -S | - | - | 0.5 | V | See Remote Sense |
| СВ | 0 | - | 3.3 | V | Sharing bus, CB to -S |
| TRIM | 0 | - | 2.5 | V | TRIM to -S |

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Electrical Specifications

| Parameter | Min. | Тур. | Max. | Unit | Notes & Conditions |
|---|------|------|------|------------------|--|
| Other characteristics | | | | | |
| Input voltage reported precision | -10 | - | 10 | V | $T_A = 25^{\circ}C, V_{in} = 90 - 290 V AC$ |
| Insulation characteristics | - | | | | |
| Input to output insulation voltage | - | - | 4242 | V DC | Reinforced insulation: |
| Input to baseplate insulation voltage | - | - | 3535 | V DC | The leakage current should be less than 10 mA, test voltage ramp up less than 500 V/S |
| Output to baseplate insulation voltage | - | - | 707 | V DC | than 500 V/S |
| Input to output insulation resistance | 10 | - | - | MΩ | |
| Input to baseplate insulation resistance | 10 | - | - | MΩ | Normal atmospheric pressure; 90% humidity; 500 V DC |
| Output to baseplate insulation resistance | 10 | - | - | MΩ | |
| Reliability characteristics | | | | | |
| Mean time between failures (MTBF) | - | 1.2 | - | Million hours | T _{Baseplate} = 25°C, Telcordia SR332 Method 1 Case3; Normal Input/Rated Output, 80% load |

Specifications are subject to change without notice.



Characteristic Curves

Conditions: $T_A = 25^{\circ}C$.

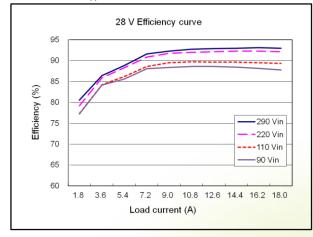
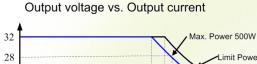
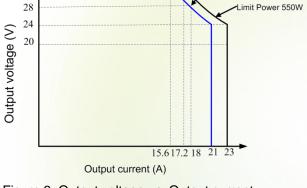


Figure 1: Efficiency







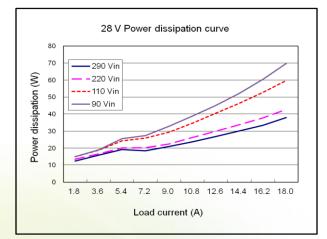


Figure 2: Power dissipation

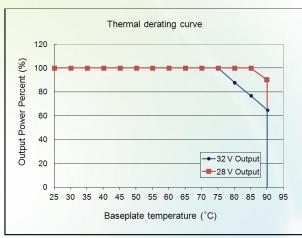


Figure 4: Thermal derating curve ($V_{in} = 110/220 V$, ambient temperature $T_A = 85^{\circ}C$)



Typical Waveforms

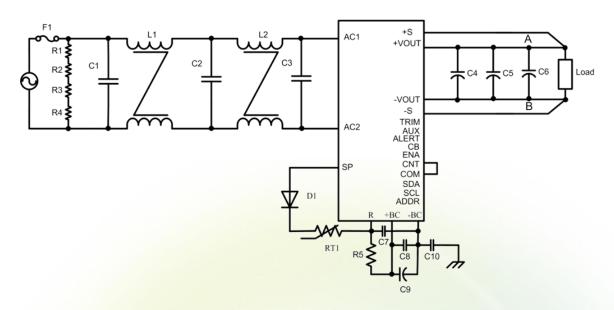


Figure 5: Test set-up diagram

F1: 15 A, 250 V AC

C1, C3: The 1 µF/275 V AC film capacitor is recommended.

C2: The 0.68 µF/275 V AC film capacitor is recommended.

C4, C5, C6: The 470 µF/63 V low ESR aluminum electrolytic capacitor is recommended.

C7, C8: The 1.5 µF/450 V film capacitor is recommended.

C9: The 390 μ F/450 V long life (5000 h) aluminum electrolytic capacitor is recommended. C10: The 2200 pF capacitor is recommended.

L1, L2: 3.5 mH

R1, R2, R3, R4: 100 kΩ/0.25 W resistor

R5: Cement resistor 75 Ω/5 W

RT1: Negative Temperature Coefficient (NTC) resistor 1 Ω

D1: 1 kV/3 A

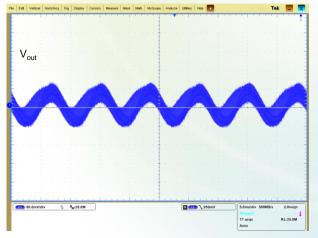


Figure 6: Output voltage ripple (For point AB in the test set-up diagram, $V_{in} = 110 V AC$, $V_{out} = 28 V$, $I_{out} = 18 A$)

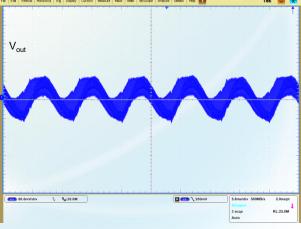


Figure 7: Output voltage ripple (For point AB in the test set-up diagram, $V_{in} = 220 V AC$, $V_{out} = 28 V$, $I_{out} = 18 A$)

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Points A and B, which are for testing the output voltage ripple, are 25 mm (0.98 in.) away from the $V_{out}(+)$ pin and the $V_{out}(-)$ pin.

Typical Waveforms

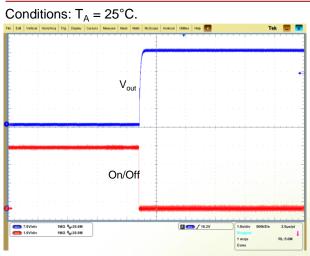
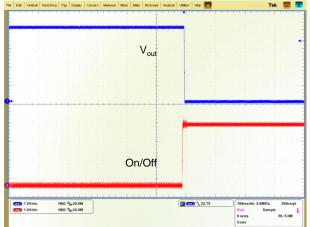
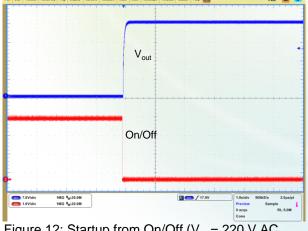
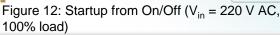


Figure 8: Startup from On/Off (V_{in} = 110 V AC, 100% load)









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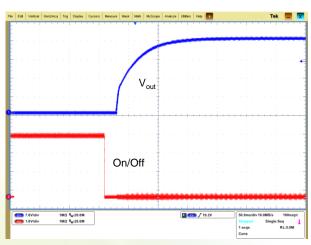


Figure 9: Startup from On/Off (V_{in} = 110 V AC, 100% load)

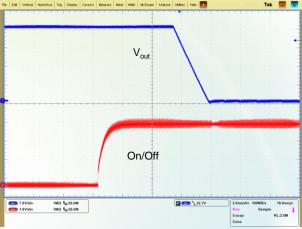


Figure 11: Shutdown from On/Off ($V_{in} = 110 \text{ V AC}$, 100% load)

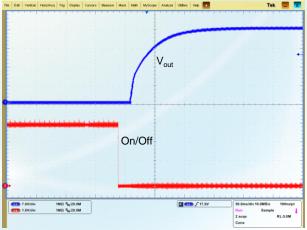


Figure 13: Startup from On/Off (V_{in} = 220 V AC, 100% load)



Typical Waveforms

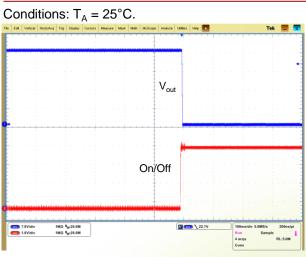


Figure 14: Shutdown from On/Off (V_{in} = 220 V AC, 100% load)

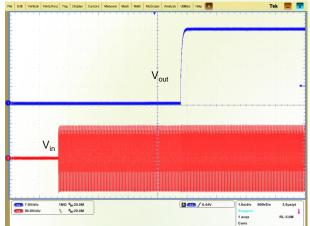


Figure 16: Startup by power on $(V_{in} = 110 \text{ V AC}, 100\% \text{ load})$

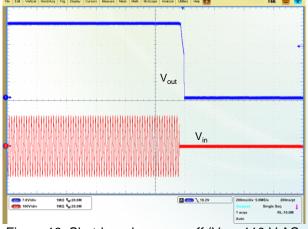


Figure 18: Shutdown by power off ($V_{in} = 110 \text{ V AC}$, 100% load)

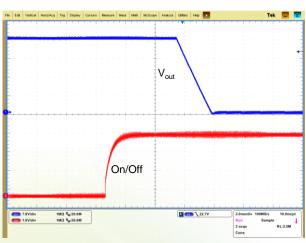


Figure 15: Shutdown from On/Off (V_{in} = 220 V AC, 100% load)

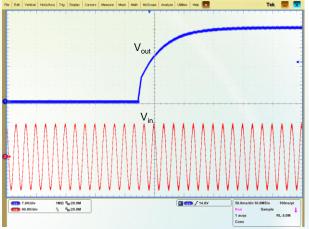


Figure 17: Startup by power on ($V_{in} = 110 \text{ V AC}$, 100% load)

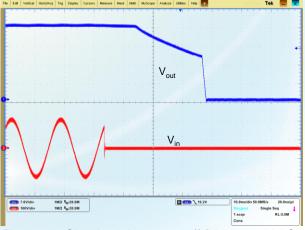


Figure 19: Shutdown by power off ($V_{in} = 110 \text{ V AC}$, 100% load)



Typical Waveforms

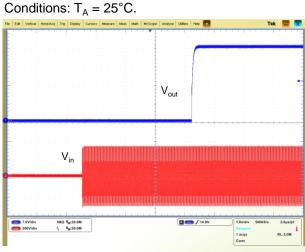
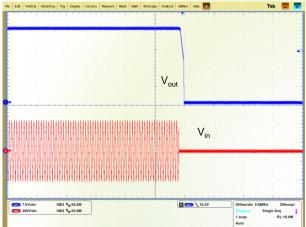
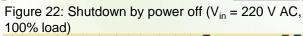


Figure 20: Startup by power on (V_{in} = 220 V AC, 100% load)





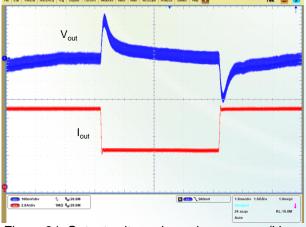


Figure 24: Output voltage dynamic response (V_{in} = 110 V AC, load: 50% - 25% - 50%, di/dt = 0.1 A/µs)

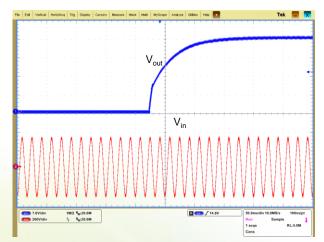


Figure 21: Startup by power on (V_{in} = 220 V AC, 100% load)

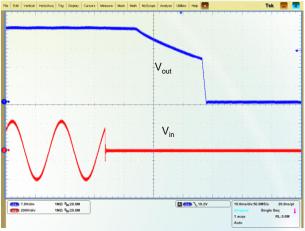


Figure 23: Shutdown by power off ($V_{in} = 220 \text{ V AC}$, 100% load)

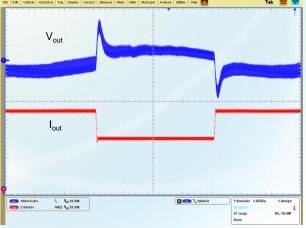


Figure 25: Output voltage dynamic response (V_{in} = 110 V AC, load: 75% - 50% - 75%, di/dt = 0.1 A/µs)



Typical Waveforms

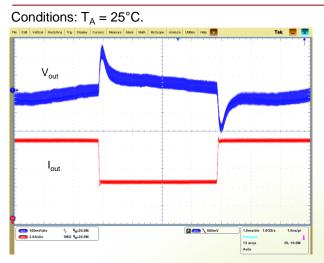


Figure 26: Output voltage dynamic response (V_{in} = 220 V AC, load: 50% - 25% - 50%, di/dt = 0.1 A/µs)

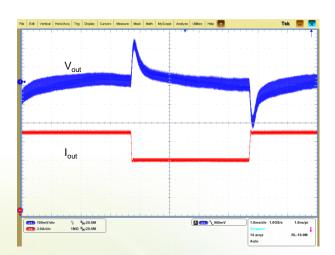


Figure 27: Output voltage dynamic response ($V_{in} = 220 \text{ V AC}$, load: 75% - 50% - 75%, di/dt = 0.1 A/µs)



Typical Circuit Application

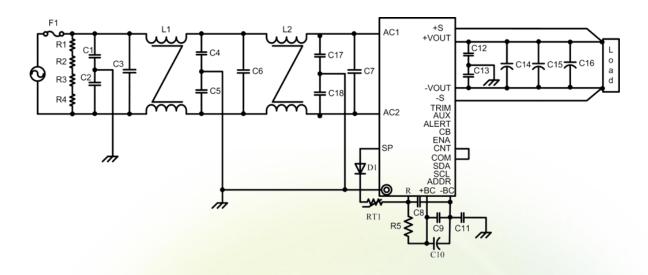


Figure 28: Typical circuit application

R1, R2, R3, R4: 0.25 W, 100 kΩ

F1: 15 A, 250 V AC

L1, L2: 3.5 mH

C1, C2: Ceramic capacitor, 1 nF, 250 V

C3, C7: Film capacitor, 1 µF, 275 V AC

C4, C5: 10 nF, 250 V AC

C6: Film capacitor, 0.68 µF, 275 V AC

C8, C9: Film capacitor, 1.5 µF, 450 V

C10: Long life (5000 h) aluminum electrolytic capacitor, 390 μF, 450 V (Recommended product model: ELXS451VSN391MR50S NCC.)
C11: 2200 pF
C12, C13: 100 nF, 1 kV
C14, C15, C16: Low ESR aluminum electrolytic capacitor, 470 μF, 63 V (Recommended product model: EKY-630ELL471MK25S NCC.)

C17, C18: 1 nF, 250 V

D1: 1 kV, 3 A

R5: Cement resistor, 5 W, 75 Ω

RT1: Negative Temperature Coefficient (NTC) resistor 1 Ω

C10, C14, C15, C16: When the temperature is lower than -25°C, double the recommended capacitor.





Remote Sense

This function is used to compensate for voltage drops on R_w . The +S, -S, $V_{out}(+)$, and $V_{out}(-)$ terminals should meet the following requirements:

$$\begin{split} [V_{out}(+) - (+S)] &\leq 5\% V_{out} \\ [(-S) - V_{out}(-)] &\leq 0.5 \ V \end{split}$$

 $(V_{out} \text{ is the rated output voltage. 20 V } \leq [V_{out}(+) - V_{out}(-)] \leq 32 \text{ V})$

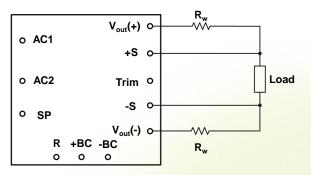


Figure 29: Configuration diagram for remote sense

 ${\sf R}_{\sf w}$ indicates the line impedance between the output terminal and the load.

If the remote sense function is disabled, the +S terminal directly connects to the $V_{out}(+)$ terminal and the -S terminal directly connects to the $V_{out}(-)$ terminal.

Output Voltage Trim

The output voltage can be adjusted according to the trim range specification by using the Trim pin.

Trim Up

The output voltage can be increased by installing an external resistor between the Trim pin and the +S pin.

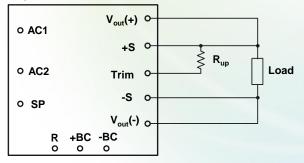


Figure 30: Configuration diagram for Trim up

The relationship between R_{up} and V_{out}:

$$R_{up} = \frac{26550 \times V_{out}}{V_{out} - 28} - 3300(\Omega)$$

Trim Down

The output voltage can be decreased by installing an external resistor between the Trim pin and the -S pin.

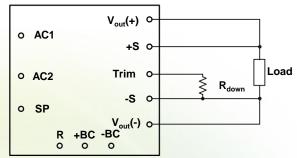


Figure 31: Configuration diagram for Trim down The relationship between R_{down} and V_{out}:

$$R_{down} = \frac{2000 \times V_{out}}{28 - V_{out}} - 3300(\Omega)$$

1

- 1. If the Trim pin is not used, it should be left open.
- When the output voltage adjustment is used, be sure not to exceed the output voltage range; otherwise, the protection function will be activated.
- 3. Ensure that the actual output power does not exceed the maximum output power when raising the voltage.

Enable (ENA)

Enable signal means that the output voltage of the inverter is normal and can supply power for load at the second side (Maximum sink current is 10 mA and maximum applied voltage is 75 V). When output voltage goes over 15 V at start up, ENA signal is low level; when output voltage drops below 13 V or input power failure, ENA signal is high resistance. The logic of Enable is as following:

| Logic Enable | ENA | Output Voltage |
|-------------------|--------------------|---|
| Negative Logic | High resistance | ≤ 13 V or Input fault, input power failure |
| | Low resistance | > 15 V |



Enable (ENA)

The enable signal is pulled up to the AUX by a 10 $k\Omega$ external resistor, indicated by an LED. The recommended circuit diagram of enable is shown in Figure 32:

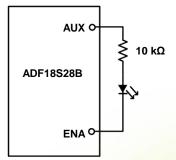


Figure 32: Recommended circuit diagram of Enable

Remote CNT (On/Off)

Remote control function realizes output enable or disable without turning the input power supply on and off. When this output On/Off control is not used, be sure to short CNT to COM terminal. The logic of On/Off are as following:

| Logic Enable | On/Off | 28 V Output |
|-------------------|-------------------------|----------------|
| Negative Logic | Low level | On |
| | High level or left open | Off |

The configuration diagram of CNT (On/Off) is as following:

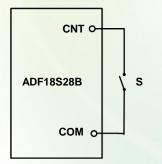


Figure 33: Configuration diagram of CNT (On/Off) signal

Auxiliary Power Supply (AUX)

The AUX terminal supplies auxiliary power for an external circuit with a typical output voltage of 12 V. Be careful not to short-circuit the AUX terminal and other terminals or the power module; otherwise, the power module would be damaged. Do not connect the AUX terminal if you do not need to supply power to any external circuit.

Parallel Operation (CB terminal)

When several power modules are used in parallel, an output current can be equally drawn from each one by connecting the CB terminals of all modules. A maximum of two units of the same module can be connected. The output power of two modules connected in parallel is equal to or less than 90% of the power of two fully loaded modules.

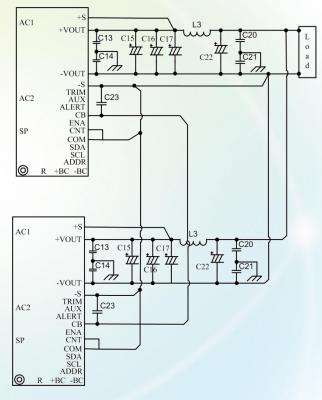


Figure 34: The circuit for parallel operation

- 1. L3: High frequency inductor 0.3 µH
- 2. C22: Aluminum electrolytic capacitor 63 V, 470 µF
- 3. C23: 1 µF, 16 V
- 4. Other capacitor parameters see EMC.



PMBus Communication

The converter communicates with the system over the PMBus. PMBus address with the following table:

| R (ADDR pull-down resistor) | Address |
|-----------------------------|---------|
| Open | Invalid |
| 200 kΩ | 0x5F |
| 174 kΩ | 0x5E |
| 150 kΩ | 0x5D |
| 124 kΩ | 0x5C |
| 100 kΩ | 0x5B |
| 75 kΩ | 0x5A |
| 49.9 kΩ | 0x59 |
| 24.9 kΩ | 0x58 |
| Ground | Invalid |

Bit is as follows:

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----|---------|---|---|---|---|---|------------|---|
| - | Address | | | | | | Read/Write | |

Monitor and Faults

The converter communicates with the system over the PMBus. The ADF18S28B provides the following monitoring and communication functions and fault detection functions:

Monitoring functions:

- Module information
- Input voltage
- Input power
- Output voltage
- Output power
- Baseplate temperature
- CNT (On/Off)

Faults detection functions:

- Reports faults for input faults
- Reports faults for output overvoltage
- Reports faults for output overcurrent
- Reports faults for baseplate overtemperature

SCL and SDA

The SCL and SDA signal has an internal pull-up resistor, connected to the communication bus through the fault isolation circuit. Figure 35 shows the SCL and SDA connection diagram.

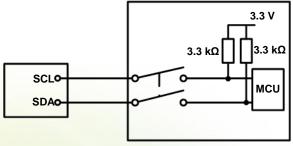


Figure 35: SCL and SDA connection diagram

PMBus Timing Diagram

The power supply supports both 100 kHz and 400 kHz clock rates, and 100 kHz is the default one. T_{set} is the duration for which SDA keeps its value unchanged before SCL increases. T_{hold} is the duration for which SDA keeps its value unchanged after SCL decreases. The communication will fail if the time is not consistent with the specifications.

The following table lists the timing characteristics of the PMBus communications interface and Figure 36 shows the timing diagram of the interface.

| Parameter | Min. | Тур. | Max. | Unit |
|--|-------|------|------|------|
| Logic Input Low (V _{IL}) | - | 1 | 1.1 | V |
| Logic Input High (V _{IH}) | 2.1 | | - | V |
| Logic output Low (V _{OL}) | - | - | 0.25 | V |
| Logic output High (V _{OH}) | 2.7 | - | - | V |
| PMBus setting-up time | 100 | | - | ns |
| PMBus holding time | 0 | - | - | ns |
| Clock/data fall time (t _f) | 20+ | - | 300 | ns |
| Clock/data rise time (t _r) | 0.1Cb | - | 300 | ns |
| Total capacitance of one bus line (Cb) | - | - | 400 | pF |



PMBus Communication

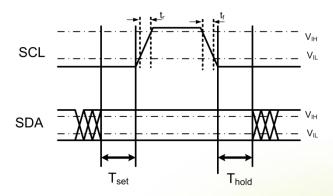


Figure 36: PMBus timing diagram

PMBus Commands

| Hex Code | Command Name | Data Type | Data Byte | Data Format |
|-------------|----------------------------|--------------------|--------------|----------------|
| Contr | ol commands | | | |
| 01h | OPERATION | Read/Write Byte | 1 | - |
| 03h | CLEAR_FAU LTS | Send Byte | 0 | - |
| Outpu | it commands | | | |
| 20h | VOUT_MOD E | Read Byte | 1 | - |
| | VOUT_COM MAND | Read/Write Word | 2 | Linear 16 |
| Alarm | commands | | | |
| 51h | OT_WARN_ LIMIT | Read/Write Word | 2 | Linear 11 |
| Status | s commands | | | - |
| 79h | STATUS_W ORD | Read Word | 2 | - |
| Monit | oring comma | nds | - | - |
| 88h | READ_VIN | Read Word | 2 | Linear 11 |
| 8Bh | READ_VOU T | Read Word | 2 | Linear 16 |
| 8Ch | READ_IOUT | Read Word | 2 | Linear 11 |
| 8Dh | READ_TEM PERATURE_ 1 | Read Word | 2 | Linear 11 |
| 96h | READ_POU T | Read Word | 2 | Linear 11 |

| - | Command Name | Data Type | | Data Format | | | |
|-------|-----------------------------------|-------------|---|--|--|--|--|
| Monit | Monitoring commands | | | | | | |
| 97h | READ_PIN | Read Word | 2 | Linear 11 | | | |
| 98h | PMBUS_RE VISION | Read Byte | 1 | - | | | |
| E9h | MFR_STATU S_WORD | Read Word | 2 | - | | | |
| ECh | MFR_WRITE _SYSTIME | Write Block | 4 | Time: S Low byte | | | |
| EFh | MFR_READ _LAST_ACD ROP_TIME | Read Block | 8 | in the former, the high byte in the post | | | |
| F6h | WRITE_STA NDBY | Write Byte | 1 | 0x20: RESET 0x00: Standby | | | |

Data Format

Linear 11 Data Format

The linear data format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent or scaling factor, as shown in the following Figure 37.

| ← | - | Dat | te E | lyte | Hi | gh | _ | → | ← | - D | ate | Ву | te l | _ov | / | → |
|---------|-----|-----|------|------|----|----|----|---|---|------------|-----|----|------|-----|---|---|
| 7 | 6 | 5 | 4 | 3 | | 2 | 1 | 0 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| [← M | ISB | - | 1- | _ | _→ | ← | SB | | | _ | Υ | _ | | | | → |

Figure 37: Linear 11 Data Format

The relationship between the N, Y, and actual value is given by the following equation:

$$X = Y \times 2^{\circ}$$

X is the value Y is the 11-bit, two's complement mantissa. N is the 5-bit, two's complement exponent.

VOUT Data Format

where

Commands related to output voltage are the VOUT_COMMAND, VOUT_MODE and READ_VOUT. They are unsigned integers using the Linear 16 formats, as shown in the following Figure 38.



PMBus Communication

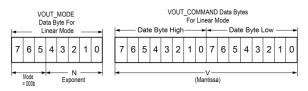


Figure 38: VOUT Data Format

The power supply is not required to support the VOUT_COMMAND, but must adhere to the VOUT data format. The output voltage is calculated as follows:

Voltage = $V \times 2^{N}$

where

Voltage is the output voltage value.

V is the 16-bit unsigned integer.

N is the 5-bit signed integer (two's complement).

Command Descriptions

OPERATION (01h): By default the Power supply is turned ON at power up as long as Enable is active low.

The Operation command is used to turn the Power Supply ON or OFF via the PMBus. The data byte below follows the OPERATION command.

| Function | Data Byte |
|----------|-----------|
| ON | 0x80 |
| RESET | 0x00 |
| OFF | 0x55 |

To RESET the power supply cycle the power supply OFF, wait at least 10 seconds, and then turn ON. All alarms and shutdowns are cleared during a restart.

CLEAR_FAULTS (03h): This command clears the latch fault bits.

VOUT_MODE (20h): This command is used to determine the data type and parameters using PMBus command.

VOUT_COMMAND (21h): This command is used to change the output voltage of the power supply. The default value is 28 V. Voltage margin range: 20 V - 32 V.

STATUS_WORD (79h): Module fault information, latch off.

| Bit | Fault Name | Fault Definition | | | |
|----------|----------------------|-----------------------------------|--|--|--|
| b15 - b6 | - | - | | | |
| b5 | VOUT_OV | 1 - Overvoltage 0 - Normal | | | |
| b4 | IOUT_OC | 1 - Overcurrent 0 - Normal | | | |
| b3 | - | - | | | |
| b2 | OVER_TEMP ERATURE | 1 - Overtemperature 0 - Normal | | | |
| b0, b1 | - | - | | | |

MFR_STATUS_WORD (E9h): Power state. Don't latch.

| Bit | Fault Name | Fault Definition |
|----------|------------------|-------------------|
| b15 - b1 | - | - |
| b0 | REMOTE ON/OFF | 1 - OFF 0 - ON |

MFR_WRITE_SYSTIME (ECh): As the converter does not have a time chip. The system uses the ECh command to deliver the system time to the converter. The converter then runs based on the delivered system time in unit of seconds. To ensure time accuracy, it is recommended that the system synchronize time to the converter every 10 minutes. The MFR_WRITE_SYSTIME command format is shown in Figure 39:

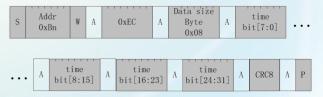


Figure 39: MFR WRITE SYSTIME command format

S: Start Condition; R: Read bit value of 1; W: Write bit value of 0; A: Acknowledge bit, may be ACK or NACK; P: Stop Condition.



PMBus Communication

MFR_READ_LAST_ACDROP_TIME (EFh): The converter can record the last disconnection time. It reads the time using the EFh command. The EFh data format is shown in the figure. The time occupies four bytes and the high-oder byte takes precedence over the low-order byte during transmission.

The MFR_READ_LAST_ACDROP_TIME command format is shown in Figure 40:



Figure 40: MFR_READ_LAST_ACDROP_TIME command format

The converter uses 8-bit cyclic redundancy check (CRC). The generator polynomial is C(x) = x8 + x2 + x1 + 1, or 0b100000111 if expressed in binary form.

The power supply is compliant with the Power Management Bus (PMBus) Protocol Specification rev1.2 requirements. For details about the PMBus Commands, see the **PMBus Protocol Specification rev1.2**.

Input Overvoltage Protection

The converter will shut down after the input voltage exceeds the input overvoltage protection threshold for shutdown. The converter will start to work again after the input voltage reaches the input overvoltage recovery threshold for startup. For the Hysteresis, see the **Protection characteristics**.

Input Undervoltage Protection

The converter will shut down after the input voltage drops below the undervoltage protection threshold for shutdown. The converter will start to work again after the input voltage reaches the input undervoltage recovery threshold for startup. For the Hysteresis, see the **Protection characteristics**.

Output Overvoltage Protection

When the voltage directly across the output pins exceeds the output overvoltage protection threshold, the converter will enter hiccup mode. If the converter experiences five or more times of overvoltage due to an internal fault within 20s, the converter locks out. You need to restart the converter to unlock it. It must be more than 20s since input source power-off to power-on. The converter dynamic overvoltage does not exceed 39 V.

Output Overcurrent Protection

When the output current exceeds the output overcurrent protection threshold, the converter will enter a hiccup mode. When the fault condition is removed, the converter will automatically restart.

Overtemperature Protection

A temperature sensor on the converter senses the average temperature of the module. It protects the converter from being damaged at high temperatures. When the temperature exceeds the overtemperature protection threshold, the output will shut down. If the temperature falls by or below the overtemperature protection recovery threshold more than 5 minutes after the converter shuts down, the output recovers. Note that the sensor does not sense the temperature within 5 minutes after the output shuts down. Therefore, even if the temperature falls to a very low level within 5 minutes after the output shuts down, there is still no output.

Cooling Characteristics

When the power module is running, the temperature of the baseplate must not exceed 90°C. The power module supports natural cooling and fan cooling. Customers can select heat sink models depending on the onsite conditions.





EMC

Figure 41 shows the EMC test set-up diagram. The acceptance standard is required as the conducted emission limits of CISPR22 Class B with 6 dB margin. The operation with Surges/Impulse Current, the level of Surge is CM/DM 6 kV/6 kV 2 Ω (1.2/50), and the level of Impulse Current is CM/DM 5 kA/5 kA (8/20).

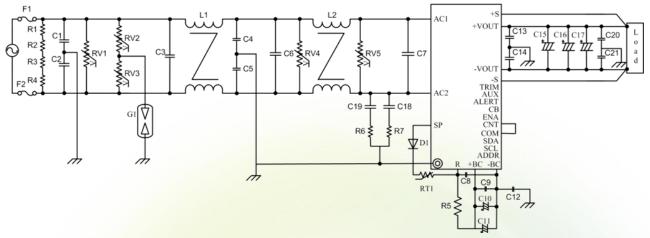


Figure 41: EMC test set-up diagram

R1, R2, R3, R4: 0.25 W, 100 kΩ RV1: 620 V - 385 V - 12 kA RV2, RV3: 750 V - 460 V - 12 kA RV4: 620 V - 385 V - 12 kA RV5: 620 V - 385 V - 4.5 kA

L1, L2: 3.5 mH, 220 V, 10 A C1, C2: Ceramic capacitor, 1 nF, 250 V C3, C7: Film capacitor, 1 µF, 275 V AC C4, C5: 0.01 µF, 250 V C6: Film capacitor, 0.68 µF, 275 V AC C8, C9: Film capacitor, 1.5 µF, 450 V C10, C11: Long life (5000 h) aluminum electrolytic capacitor, 390 µF, 450 V (Recommended product model: ELXS451VSN391MR50S NCC.) C12: 2200 pF C13, C14: 100 nF, 1 kV C15, C16, C17: Low ESR aluminum electrolytic capacitor, 470 µF, 63 V (Recommended product model: EKY-630ELL471MK25S NCC.) C18, C19: 1 nF, 250 V C20, C21: 22 nF, 1 kV D1: 1 kV, 3 A R5: Cement resistor, 5 W, 75 Ω

R6, R7: 0.25 W, 22 Ω RT1: Negative Temperature Coefficient (NTC) resistor 1 Ω G1: 10 kA, 1.5 kV F1, F2: 15 A, 250 V AC

C10, C11, C15, C16, C17: When the temperature is lower than -25°C, double the recommended capacitor.

GLOBAL ENERGY EFFICIENCY SPECIALIST



Qualification Testing

| Parameter Units | | Condition | | | |
|---|--|---|--|--|--|
| High Accelerated Life Test (HALT) 6 | | Low temperature limit: -60°C; high temperature limit: 110°C; vibration limit: 40 G; temperature slope: 40°C per minute; vibration frequency range: 10 Hz - 10000 Hz | | | |
| Temperature Humidity Bias (THB)12 | | Maximum input voltage; 85°C; 85% RH; 1000 operating hours under lowest load power | | | |
| High Temperature Operation Bias (HTOB) | | Rated input voltage; air flow: 0.5 m/s (100 LFM) to 5 m/s (1000 LFM); ambient temperature between +45°C and +55°C; 1000 operating hours; 50% to 80% load | | | |
| Power and Temperature Cycling Test (PTC) | | Rated input voltage; air flow: 0.5 m/s (100 LFM) to 5 m/s (1000 LFM); ambient temperature between -40°C and +85°C; 1000 operating hours; 50% load; temperature slope: 15°C per minute; dwell time: 22 minutes | | | |

Thermal Consideration

Thermal Test Point

Sufficient airflow should be provided to ensure reliable operating of the converter. Therefore, thermal components are mounted on the top surface of the converter to dissipate heat to the surrounding environment by conduction, convection and radiation. Proper airflow can be verified by measuring the temperature at the middle of the baseplate.



Figure 42: Thermal test point

Power Dissipation

The converter power dissipation is calculated based on efficiency. The following formula reflects the relationship between the consumed power (P_d), efficiency (η), and output power (P_o): $P_d = P_o(1-\eta)/\eta$



Mechanical Consideration

Installation

Although the converter can be mounted in any direction, free airflow must be taken.

Soldering

The converter is compatible with standard wave soldering or hand soldering. No reflow soldering is allowed.

- 1. For wave soldering, the temperature on converter is specified to maximum 260°C for maximum 7 seconds.
- 2. For hand soldering, the iron temperature should be maintained at 350°C to 420°C, and applied to the converter pins for less than 10 seconds.

The converter can be rinsed using the isopropyl alcohol (IPA) solvent or other proper solvents.

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